

A New Extended DKP Hierarchy and Generalized Dressing Approach

Yuqin Yao^a

February 12, 2009

a. Department of Mathematical Sciences, Tsinghua University, Beijing, 100084,
 PR China.

(with Xiaojun Liu)

Let $L = \Delta + f_0 + f_1\Delta^{-1} + f_2\Delta^{-2} + \dots$, $B_n = L_+^n$, the DKP hierarchy reads[1,2]

$$L_{t_n} = [B_n, L].$$

Inspired by the squared eigenfunction symmetry constraint [3], we propose

Proposition 1. The extended DKP hierarchy (exDKPH) is constructed as follows

$$L_{t_n} = [B_n, L] \quad (1a)$$

$$L_{\tau_k} = [B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i, L] \quad (1b)$$

$$\psi_{i,t_n} = B_n(\psi_i), \quad \phi_{i,t_n} = -B_n^*(\phi_i), \quad i = 1, \dots, N. \quad (1c)$$

Under (1c), the commutativity of (1a) and (1b) leads to the zero curvature equation for the exDKPH

$$B_{n,\tau_k} - (B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i)_{t_n} + [B_n, B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i] = 0, \quad (2a)$$

$$\psi_{i,t_n} = B_n(\psi_i), \quad \phi_{i,t_n} = -B_n^*(\phi_i), \quad i = 1, 2, \dots, N. \quad (2b)$$

and its Lax representation

$$\Psi_{t_n} = B_n(\Psi), \quad \Psi_{\tau_k} = (B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i)(\Psi). \quad (3)$$

(2) contains two types of DKP equation with self-consistent sources(DKPESCS).

The t_n -reduction of the exDKPH leads to

$$B_{n,\tau_k} = [(B_n)_+^{\frac{k}{n}} + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i, B_n], \quad (4a)$$

$$B_n(\psi_i) = \lambda_i^n \psi_i, \quad B_n^*(\phi_i) = \lambda_i^n \phi_i, \quad i = 1, 2, \dots, N. \quad (4b)$$

The τ_k -reduction leads to

$$(B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i)_{t_n} = [(B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i)_{+}^{\frac{n}{k}}, B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i], \quad (5a)$$

$$\psi_{i,t_n} = (B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i)_{+}^{\frac{n}{k}}(\psi_i), \quad (5b)$$

$$\phi_{i,t_n} = -(B_k + \sum_{i=1}^N \psi_i \Delta^{-1} \phi_i)_{+}^{\frac{n}{k}*}(\phi_i), \quad i = 1, 2, \dots, N. \quad (5c)$$

Assume that L of exDKPH can be written in the dressing form: $L = W \Delta W^{-1}$. In this paper, we propose a generalized dressing approach for solving the exDKPH.

Proposition 2. Let f_i, g_i satisfy

$$f_{i,t_n} = \Delta^n(f_i), \quad f_{i,\tau_k} = \Delta^k(f_i) \quad (i = 1, \dots, N) \quad (6a)$$

$$g_{i,t_n} = \Delta^n(g_i), \quad g_{i,\tau_k} = \Delta^k(g_i). \quad (6b)$$

$$h_i = f_i + \alpha_i(\tau_k)g_i \quad i = 1, \dots, N \quad (7)$$

$$W = \frac{1}{Wrd(h_1, \dots, h_N)} \begin{vmatrix} h_1 & h_2 & \cdots & h_N & 1 \\ \Delta(h_1) & \Delta(h_2) & \cdots & \Delta(h_N) & \Delta \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \Delta^N(h_1) & \Delta^N(h_2) & \cdots & \Delta^N(h_N) & \Delta^N \end{vmatrix} \quad (8)$$

$$Wrd(h_1, \dots, h_N) = \begin{vmatrix} h_1 & h_2 & \cdots & h_N \\ \Delta(h_1) & \Delta(h_2) & \cdots & \Delta(h_N) \\ \vdots & \vdots & \vdots & \vdots \\ \Delta^{N-1}(h_1) & \Delta^{N-1}(h_2) & \cdots & \Delta^{N-1}(h_N) \end{vmatrix} \quad (9)$$

$$\psi_i = -\alpha_i W(g_i) \quad \phi_i = (-1)^{N-i} \frac{Wrd(\Gamma h_1, \dots, \hat{\Gamma} h_i, \dots, \Gamma h_N)}{Wrd(\Gamma h_1, \dots, \Gamma h_N)}, \quad i = 1, \dots, N \quad (10)$$

then W, L, ψ_i and ϕ_i satisfy (1).

By using Proposition 2, some soliton solutions for two types of DKPESCS are obtained.

References

- [1] K. M. Tamizhmani and S. Kanaga Vel, *Chaos Soliton and Fractal*, **11**, 137 (2000).
- [2] J. S. He, S. W. Liu and Y. Cheng. The determinant representation of the gauge transformation for discrete KP hierarchy, preparation.
- [3] W.Oevel. Darboux transformation for integrable lattice system, *Nonlinear Physics. Theory and Experiment*, 233-240, E. Alfinito, L.Martina and F. Pempinelli(eds), World Scientific, Singapore (1996).